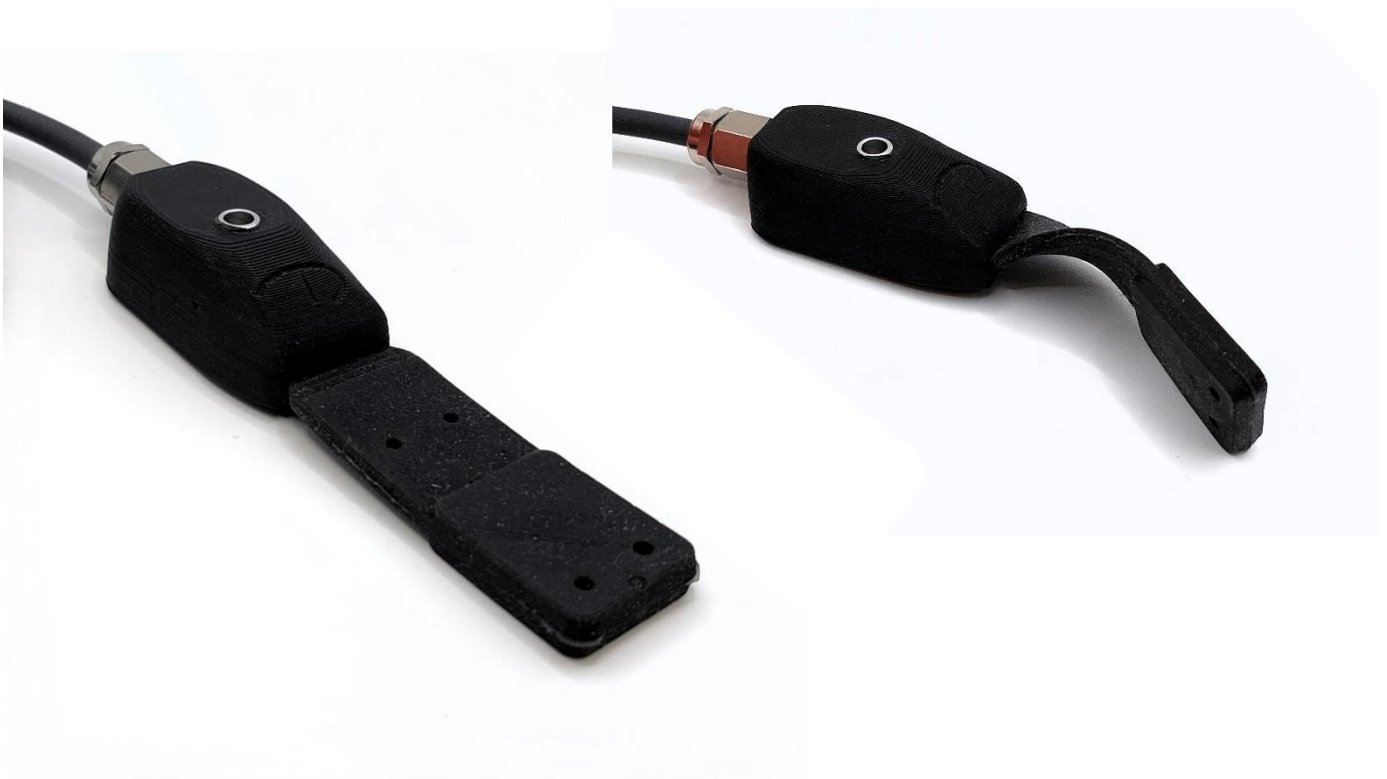# Tactile Sensor

Datasheet

Properties

The rubbery structure allows it to be attached to any surface, regardless of its shape (straight, curved, irregular). The softness of the sensor makes it ideal for contact with any object that needs to be gripped and where the contact force needs to be measured. Understanding the gripping force makes the process faster and more reliable and prevents damage to sensitive parts. It is equipped with a versatile electronic that provides analog output as well as digital communication and IOs.

- Flexible rubber-like sensor that can be mounted on surfaces of any shape
- Its flexibility even allows it to be mounted on the joints and hinges of a gripper
- The softness of the sensor protects fragile objects
- Ultra-low weight
- No additional measuring amplifier required
- Intelligent electronics with digital IOs, analog output and/or digital communication
- Compact design

Applications

- Pick and place
- Gripping & Clamping
- Soft robotics and soft grippers
- Robotics in general
- High Resolution Displacement Measurement

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Tactile Sensor

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Technical Data

- Different information within one row describes orderable options, see chapter ordering code for details.
- All the following information represents our technical standard. Other configurations/specifications are available on request.

Mechanical and Environmental Data

Parameter	Symbol	Value		Unit	Comments
Measurement Range	p_{FS}	250		kPa	
Weight	m	~ 25		g	Sensor with electronic
Electrical Connection		M8 5-pin	Bare Ends		
Operating Temperature	T_{op}	-55 … 80		°C	Up to 150°C with separate electronic
Storage Temperature	T_{st}	0 … 30		°C	
IP Classification		w/o	IP68		

Electrical Data

Parameter		Symbol	Value			Unit	Comments
Supply Voltage		V_{sup}	12	24	9 … 30	V	Tolerance ±20%
Power Consumption		P_{tot}	≤ 1			W	
Analog Outputs		V_{out}	0 … 10			V	limited by V_{sup}
		I_{out}		0 … 20	4 … 20	mA	Current Output: $R_{sink} \leq \frac{V_{sup} - 2\,V}{0.02\,A}$
Electrical Resolution			12			bit	Resolution of DAC
Communication			UART				Adapter (PRA) is required
Digital IOs	Input	V_{IL}	$0 < V_{IL} \leq 2$			V	Logical Low
		V_{IH}	$10 < V_{IH} \leq 24$			V	Logical High
	Output		Open Drain				Output characteristics
		V_{OL}	< 2			V	
		I_{OL}	< 250			mA	
		V_{OH}	< 30			V	Pullup dependent
		R_{pull}	∞		10	kΩ	Sensor internally to V_{sup}

Performance Data

Parameter	Symbol	Value	Unit	Comments
Sampling Frequency*	f_s	≤1	kHz	Maximum refresh rate of analog output
Resolution		40	g	Smallest detectable output with a 'standard finger' (r = 6 mm)

*Specifications performed at 125 Hz
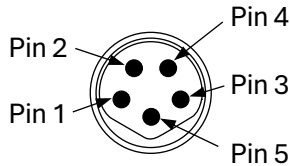
Tactile Sensor

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Materials

Part	Material
Housing	PLA
Cable	PVC
Bushings	Stainless Steel
Sensor element	PDMS
Others	TPU, nickel-plated brass, CR/NBR, FKM

Please contact us for further information.

Other Materials are available on request.

Electrical Connection

M8 Connector (5M8V & 5M8D)

Pin 1: Supply voltage
Pin 2: DIO 0
Pin 3: Ground
Pin 4: DIO 1
Pin 5: Analog Out

IEC 61076-2-104 B-coded M8

Bear Ends (5BED)

White: Supply Voltage
Brown: DIO 0
Green: Ground
Yellow: DIO 1
Gray: Analog Out

Other electrical connections are available on request!

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Tactile Sensor

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Mechanical Dimensions

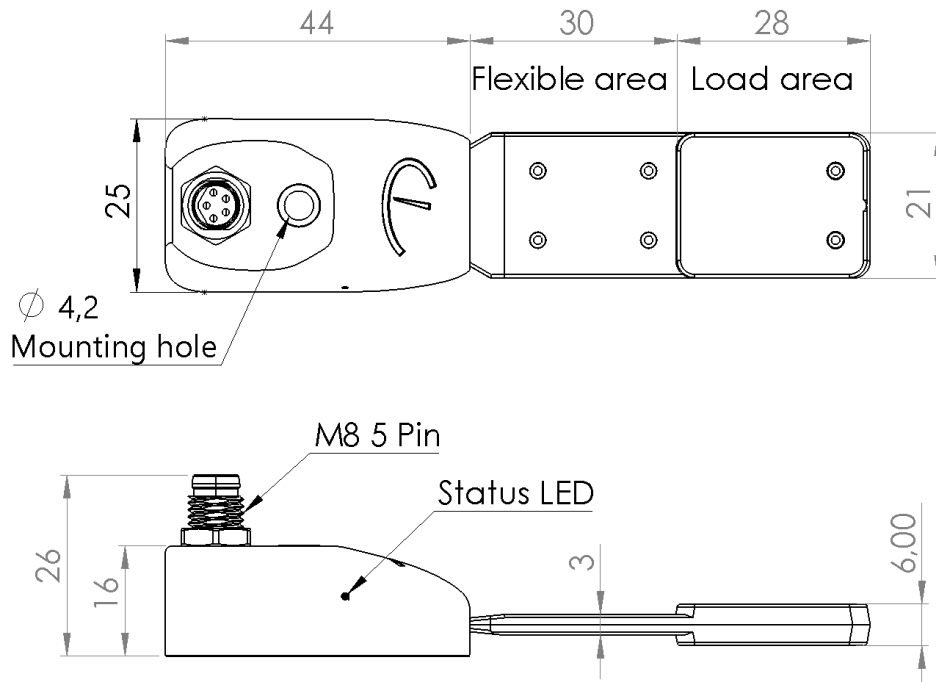### M8 5-pin connector in housing (5M8V)

Figure 1: Drawing of Sensor 5M8V - M8 Male plug in housing
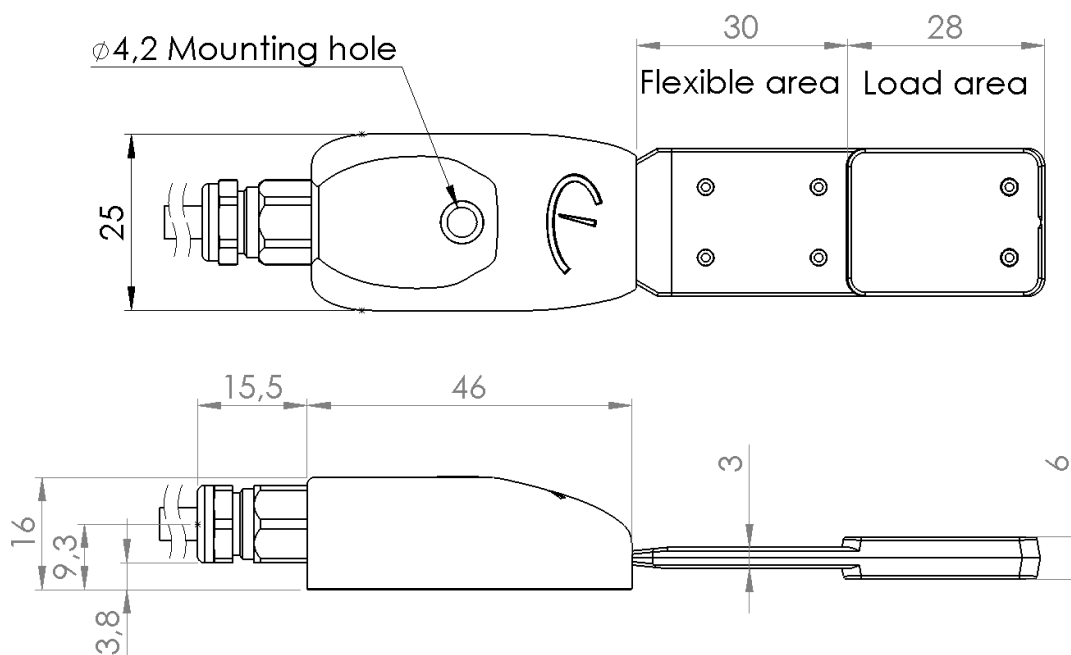
Cabled versions (5BED & 5M8D)

Figure 2: Drawing of Sensor 5M8C & 5BEC – Cabled version

Other lengths or mounting conditions are available on request!

Tactile Sensor

Datasheet

Order Code

DLO - S1M4 - 2128 - 5M8V - 24 - 2H - I0 - 00 - XXXX

Type		
DLO	Delfa Load System	
Housing Type		
S1M4	PA12, M4 with Stainless steel bushings	
Range		
2128	Tactile	
Electrical Connection		
5M8V	M8 Male plug in housing IEC 61076-2-104 b-coded	
5M8D	2 m cable with male M8 plug IEC 61076-2-104 b-coded	
5BED	2 m cable with bare ends	
Supply Voltage *1)		
12	12 VDC	
24	24 VDC	
9X	9 - 30 VDC	
Sampling Rate		
1X	10 Hz	
1C	100 Hz	
2H	250 Hz	
5H	500 Hz	
1K	1.000 Hz	
Analog Output		
00	w/o	
U1	0 - 10 V	
I0	0 - 20 mA	
I4	4 - 20 mA	
Digital Ports *2)		
00	w/o	
2I	Two digital Inputs to teach	
IO	one Input, one Output	
2O	Two digital Outputs	Standard Product
Optional Features (separate table)		

Other options (sensor range, supply & output voltage, housing, communication, cable lengths, ...) available on request.

*1) Maximum analog output limited by supply voltage

*2) Digital ports are preconfigured, programming adapter PA-GPIO is recommended to adjust limits via software

Optional Features

Multiple selection possible, add corresponding suffix to end of order code without separator.
Leave blank if no options are desired.

Order code table	
PU	Digital Output: 10 kΩ Pull-up (Only available when Digital Output(s) is/are chosen.)
IP	IP68 protection(*), only available for cabled versions (e.g. 5M8D, 5BED)

(*): Development in progress, please contact us for further information

Customer-specific sensor systems are assigned a factory order code.

Digital IO's and Communication

- All digital outputs are open drain low-switching (NPN) type, external pull-up is required. (An internal 10 kΩ Pull-up is available as an optional feature)
- By default, the digital outputs are high when the assigned limit is exceeded.
- By default, digital inputs react on a digital high (positive logic). Always tie unused inputs to Ground.
- Other switching options (e.g. output change to digital low when exceeding a limit; pulse instead of edge; …) are available on request.
- All limit values can be set by software with the programming adapter (PRA-GPIO) or with corresponding digital inputs.
- Outputs can be used to switch e.g. a relay, a valve, or an alarm system.

Functionality of the digital IOs according to the ordered configuration

	2I	IO	2O
DIO 0	Set min limit	Limit 1 (Output)	Limit 1
DIO 1	Set max limit	Set Limit 1 (Input)	Limit 2

Option "2I": Two digital Inputs to teach the analog output

This option enables defining the positions where the minimum and maximum analog signal should be output using the digital inputs. When an input is activated, the current position is latched as the value for the according analog signal limit. This enables the user to focus the analog output on a specific range of interest. The limits can also be adjusted using the programming adapter PRA-GPIO.
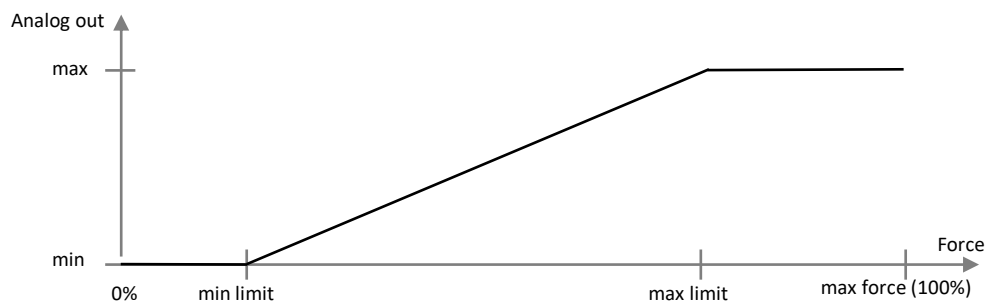

Figure 1: Analog output signal with taught limits.

Option "IO": 1 digital input to teach a limit and 1 digital output signal

This option is used for generating an alarm or control signal when a maximum displacement value, configured in software, is exceeded. It can be used to mimic a limit switch generating a digital signal output. The limit can be adjusted using the digital Input or the programming adapter PRA-GPIO.
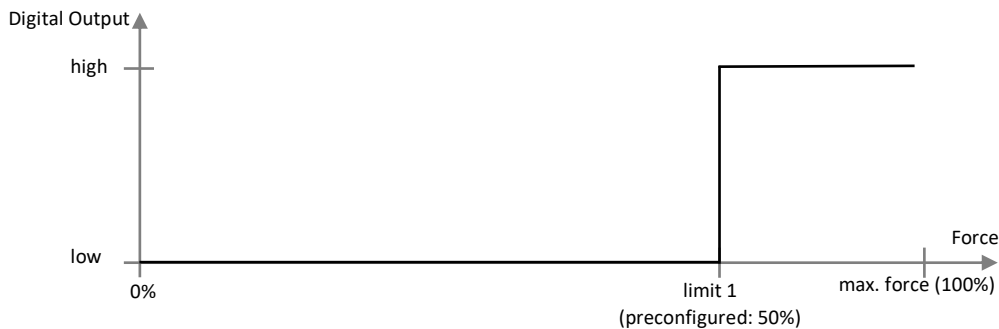

Figure 2: Digital output signal vs. force.

Option "2O": 2 digital output signals

This option is used for generating two alarm or control signals when a minimum or maximum displacement value, configured in software, is exceeded. It can be used to mimic two limit switches generating a digital signal output. The limit can be adjusted using the programming adapter PRA-GPIO.
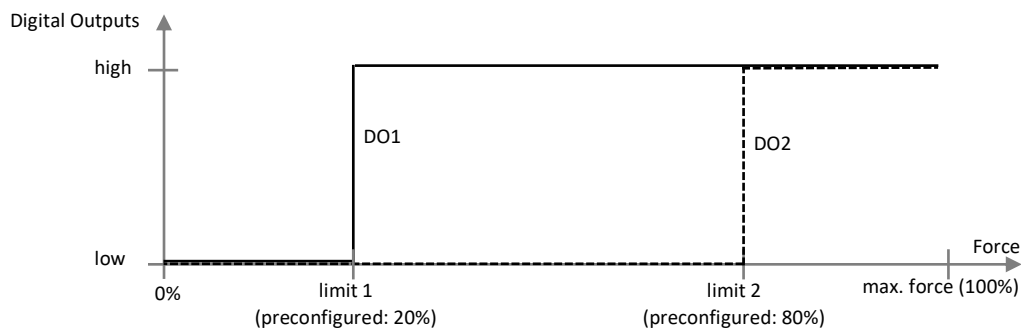

Figure 3: Digital output signals vs. force.

Analog Output

The limits for the analog output signal (i.e. the sensor position for minimum / maximum output signal) can always be changed using the programming adapter PRA-GPIO.

Please take care that the maximum voltage of the voltage output signal is limited to the supply voltage if this is less than 10 V.

This also applies to current output devices. Always select the burden resistor R_{sink} in that way, that with full output current more than 1 V between the supply and the voltage of the output pin is guaranteed (supply higher than output). This can be done by using this formula:

$$R_{sink} \leq \frac{V_{sup} - 2\,V}{0.02A}$$

Optional Features

Temperature Compensation

To improve the temperature stability, an optional temperature compensation can be ordered. If this is used, due to self-heating of the system, stability will be reached after a run-in time of approximately 15 minutes.

The performance of the compensation can be influenced by temperature differences between the electronic housing and the sensitive element e.g. due to radiant heat. For best performance, the temperature of all parts should be as close as possible.

Pullup for Digital Outputs

Additional Pullup-Resistors with a resistance of 10 kOhm between the output and the supply voltage are added.

Protection Class IP68

Extended protection of the sensor against water reaching IP68 classification. This is only available with cabled connections.

Accessories

- Programming Adapter **PRA-GPIO**
- Sensor Cable **SCA-…**
- Communication adapter for RS422/485, RS232 **PRA-COM…**